NONDIMENSIONAL PARAMETER ANALYSIS

The maximum pressure a container will withstand is a function of the material fatigue strength, the amount of prestress, the number of components N, and the wall ratios k_n . To determine the function dependence on these variables and to determine the best designs, a nondimensional analysis is now presented. The calculations for the analysis of each design were programmed on Battelle's CDC 3400 computer.

Multiring Container

Static Shear Strength Analysis

Although a fatigue criterion of failure has been chosen it is illustrative to review an analysis based upon <u>static shear strength</u> for ductile materials first conducted by Manning⁽²³⁾. The method outlined here differs from that of Manning and is more straightforward. In this analysis the optimum design is found such that <u>each</u> component of the <u>same</u> material has the <u>same</u> value of maximum shear stress S under the pressure load p. The given information is $p_0 = p$, $p_N = 0$, and K. The unknowns are the interface pressures p_n , (N-1) in number; the k_n , N in number and S. The total unknowns are 2N. There are N equations resulting from Equation (15) and having the form

$$S = (p_{n-1} - p_n) \frac{k_n^2}{k_n^{2-1}}, n = 1, 2, ..., N$$
 (26)

There is the equation, $K = k_1 k_2 \dots k_n$, that relates the k_n and K. Also N-1 equations can be formulated from the requirement that S be a minimum, i.e.,

$$\frac{\partial S}{\partial k_n} = 0, n = 1, 2, \dots, N-1$$
 (27)

(There are not N equations in the Form (27) because there is one equation relating the k_n .) Thus, there are also 2N equations which can be solved for the 2N unknowns. The solution gives

$$p_n = p_{n-1} - \frac{(k_n^2 - 1)}{k_n^2} S, \quad n = 1, 2, ..., N-1$$
 (28)

$$k_1 = k_2 = \dots = k_N$$
 (29)

$$S = \frac{p}{N} \frac{K^{2/N}}{(K^{2/N} - 1)}$$
(30)

The residual pressures q_n and the required interferences for the shrink-fit assembly have yet to be found. The radial stress σ_{rn} at the radius r_n resulting from the bore pressure p is given by Equation (13a) with K replacing k_n , p replacing p_{n-1} , r_N replacing r_n , r_n replacing r, and $p_n = p_N = 0$. σ_{rn} becomes:

$$\sigma_{rn} = \frac{p}{K^2 - 1} (1 - k_{n+1}^2 k_{n+2}^2 \dots k_N^2)$$

The pressure p_n is the sum of q_n and $(-\sigma_{rn})$. Therefore,

$$q_n = p_n - (-\sigma_{rn}) \tag{32}$$

(31)

(33)

The interference as manufactured, Δ_n at r_n , is given by

$$\frac{\Delta_n}{r_n} = \frac{-u_n(r_n)}{r_n} + \frac{u_{n+1}(r_n)}{r_n}$$

where

 $u_n(r_n) = radial deformation at <math>r_n$ of cylinder N due to the residual pressure q_n at r_n and the residual pressure q_{n-1} at r_{n-1} .

and

 $u_{n+1}(r_n) = radial deformation at r_n of cylinder n+1 due to the residual pressure <math>q_n$ at r_n and the residual pressure q_{n+1} at r_{n+1} .

Substituting the Expressions (32) for q_n into Expressions (14a) for the u_n and substituting the results into Equation (33), we find that Δ_n/r_n reduces to:

$$\frac{\Delta_n}{r_n} = \frac{2p}{NE}$$
(34)

The result p/2S given by Equation (30) is plotted in Figure 43 for various N. The limit curve is given by

$$\left(\frac{p}{2S}\right)_{1\text{imit}} = \frac{K^2 - 1}{K^2}$$
 (35)

at which limit the minimum shear stress becomes equal to -S at the bore in the inner cylinder.

Figure 43 has been obtained under the assumption that $\frac{\sigma_{\theta} - \sigma_{r}}{2}$ always gives the maximum shear stress. As pointed out by Berman, the maximum shear stress in a closed-end container* is given by $\frac{\sigma_{z} - \sigma_{r}}{2}$ when $\sigma_{z} > \sigma_{\theta}$. (42) Therefore, it is important to know the limit to $\frac{p}{25}$ for which σ_{z} becomes equal to σ_{θ} . σ_{z} is given by

^{*}Containers for hydrostatic extrusion generally are not closed-end containers. The effect of axial stress is included here for completeness.